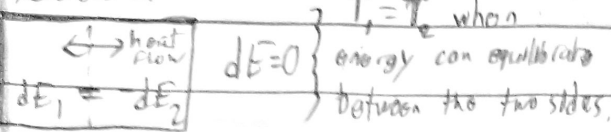


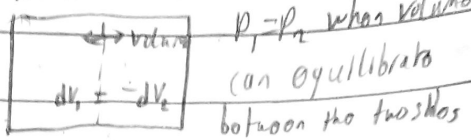
Lecture 21 review

$$W(E, V, n, \dots) \xrightarrow{\text{Ln}} S(E, V, n, \dots) \xrightarrow{\text{invert}} E(S, V, n, \dots) \rightarrow dE = \underbrace{\left(\frac{\partial E}{\partial S}\right)}_{T > 0} dS + \underbrace{\left(\frac{\partial E}{\partial V}\right)}_{-P} dV + \underbrace{\left(\frac{\partial E}{\partial n}\right)}_{\mu} dn + \dots$$

extensive variables
isolated sys



Isolated: $dV=0$



Lecture 22: E, F, G, H

E, F, G, H...; a series of functions that contain identical info but depend on different variables.

Why F, G, H... : $E(S, V, n)$ has the same info, but S, V, \dots may not be convenient.

Why not just solve $E(S) \rightarrow T = \frac{\partial E}{\partial S} = T(S)$

Doesn't work $\rightarrow E(T) = E(S(T)) \leftarrow S(T)$ (invert)

Simple formula: extensive $\rightarrow E(S, V, \dots)$

(if S, V) $\rightarrow \lambda E(S, V, \dots)$

taking derivative with respect to λ

$$\frac{\partial E}{\partial S} \frac{\partial S}{\partial \lambda} + \frac{\partial E}{\partial V} \frac{\partial V}{\partial \lambda} = \frac{\partial}{\partial \lambda} \lambda E(S, V, \dots)$$



Function	Variable	slope	intercept
Y	X	$\frac{\partial Y}{\partial X} = m$	$\phi = \frac{Y}{m}$
E	S	$\frac{\partial E}{\partial S} = T$	$F = E - TS$

$$\left(\frac{\partial E}{\partial S}\right) S + \left(\frac{\partial E}{\partial V}\right) V + \dots = E(S, V, \dots)$$

$E(T)$ or $y(m)$ loses info about the function
 $z(m) = y(m)$ even though $z(x) \neq y(x)$

true for any λ , including $\lambda=1$

$$\frac{\partial E}{\partial S} S + \frac{\partial E}{\partial V} V + \left(\frac{\partial E}{\partial n}\right) n = E(S, V, n)$$

$$y(x) = x^2 \text{ and } z(x) = (x-5)^2$$

$$\frac{\partial y}{\partial x} = m = 2x \quad \frac{\partial z}{\partial x} = m = 2(x-5)^2$$

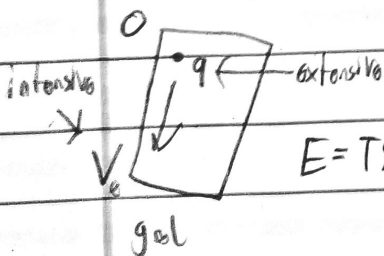
$$TS + PV + \mu n + \dots = E(S, V, n)$$

$$x = m/2 \quad (x-5) = m/2$$

$$y(x(m)) = \frac{m^2}{4} \quad z(x(m)) = \frac{m^2}{4}$$

Thought experiment: other variables

What we need instead of $E(T)$, which loses info, is a function $F(T)$ that is equivalent but preserves info.



$$E = TS - PV + \mu n + V_0 q + \dots$$

$$y(x) \xleftrightarrow{\text{S}} \phi(m)$$

$$y(x) \xrightarrow{\text{S}} y(n) \text{ can't go back}$$

$$E(S, V, n) \xrightarrow[\text{to T}]{\text{from S}} F(T, V, n) = E - TS \xrightarrow[\text{P}]{\text{from V to}} G(T, P, n) = E - TS + PV = H - TS$$

$$\xrightarrow[\text{to T}]{\text{from V to P}} H(S, P, n) = E + PV \xrightarrow[\text{to T}]{\text{from S}}$$